

# Autonomous Vehicles

Seminar on Digitalisation and the Rebound Effect

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Danil Ivanov

28.11.2019

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# Some Numbers



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- Complex Ties
- Polluting
- Inefficient
- Dangerous toward users
- Dangerous toward bystanders

State of the Art

Remaining Work

Rebound Effects

Conclusion

State of the Art

Remaining Work

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# Autonomous Vehicles

Definition<sup>1</sup>: An **autonomous vehicle** (AV) is a vehicle that is capable of sensing its environment and safely moving through it with no human input.

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<sup>1</sup>Definition based on my understanding of the domain

# Levels of Autonomy<sup>2</sup>

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<sup>2</sup>Automated Driving – Levels of Driving Automation defined in New SAE International Standard J3016. SAE International. 2014.

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- Level 0: No Assistance

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- Level 0: No Assistance
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- Level 4: Mind Off

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- Level 0: No Assistance
- Level 1: Hands On
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- Level 3: Eyes Off
- Level 4: Mind Off
- Level 5: Steering Wheel Optional

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## Example of Level 2 Automation



**Figure 1:** Tesla Autopilot

## Example of Level 4 Automation



**Figure 2:** Autonomous mini bus in Zug

# Available Technology (1)<sup>3</sup>

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- Connected Vehicles
  - GPS + IoT
  - OnStar, Android Auto, CarPlay

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- Coordinated Vehicles
  - IoT communication
  - Routing apps (Waze, Google Maps)
  - Parking apps (ParkingPay, EasyPark, Parknow)

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  - Routing apps (Waze, Google Maps)
  - Parking apps (ParkingPay, EasyPark, Parknow)
- Driverless Vehicles
  - Waymo
  - Mobility

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- Electric Vehicles
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- Electric Vehicles
  - Increased control over drive system
  - Reduced emissions
  - Popular (Tesla, Jaguar, VW, etc. . . )
- Tailored Vehicles
  - Current vehicles are over-specified and under-utilized
  - More efficient due to beign lighter
  - Longer distances on smaller batteries

State of the Art

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<sup>4</sup>Federal Roads Office FEDRO (2019), *Rechtliche Situation*

- Driver must remain in control of the vehicle at all times

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- Driver must remain in control of the vehicle at all times
- International Convention on road traffic amendment in 2006 to include automated driver assistance systems
- Presence of driver is mandatory
- Driver not exempted of their obligations and responsibilities

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World Forum for Harmonization of Vehicle Regulation has released a Framework Document<sup>5</sup> to guide the work in AV.

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- Functional requirements of automated/autonomous vehicles
- New assessment and test method

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- Functional requirements of automated/autonomous vehicles
- New assessment and test method
- Cybersecurity and software updates
- Data storage system and event data recorder

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# Case Study: Mobility Preferences in the Future<sup>6</sup>

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<sup>6</sup>Christina Pakusch, Gunnar Stevens, Alexander Boden and Paul Bossauer. Unintended Effects of Autonomous Driving: A Study on Mobility Preferences in the Future, *Sustainability*, 10 (7), 2018

## Case Study: Mobility Preferences in the Future<sup>6</sup>

- Study on mobility preference shift upon introduction of autonomous vehicles

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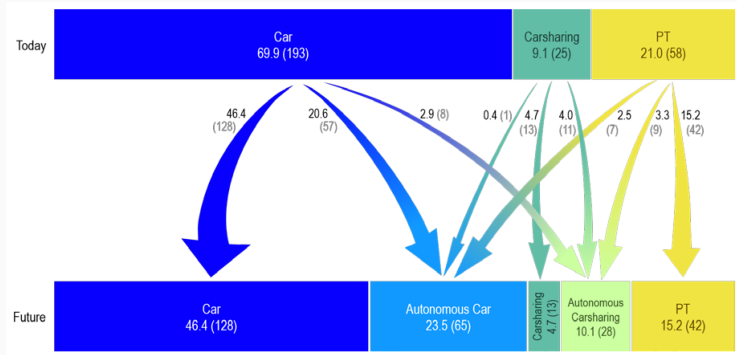
## Case Study: Mobility Preferences in the Future<sup>6</sup>

- Study on mobility preference shift upon introduction of autonomous vehicles
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- Took form of an online survey combined with paired comparison

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# Case Study: Mobility Preferences in the Future - Results



**Figure 3:** Preference migration results

## Case Study: Mobility Preferences in the Future - Conclusion

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- No intrinsic eco-friendly motivation

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- No intrinsic eco-friendly motivation
- Public Transport must improve in order to remain competitive against carsharing



# Case Study: Simulation of City-Wide Autonomous Vehicle Network Deployment<sup>7</sup>

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<sup>7</sup>Joschka Bischoff and Michal Maciewski. Simulation of City-wide Replacement of Private Cars with Autonomous Taxis in Berlin, *Procedia Computer Science*, 83, pp. 237–244, 2016

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- Simulation of autonomous vehicle fleet that replaces all classic vehicles in Berlin

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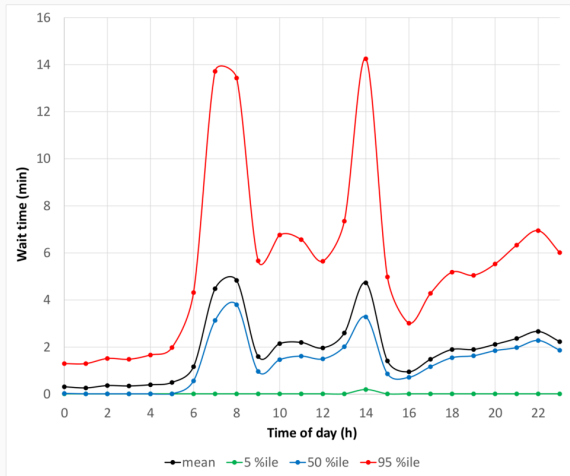
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- Goal: find optimal fleet size to provide high quality service

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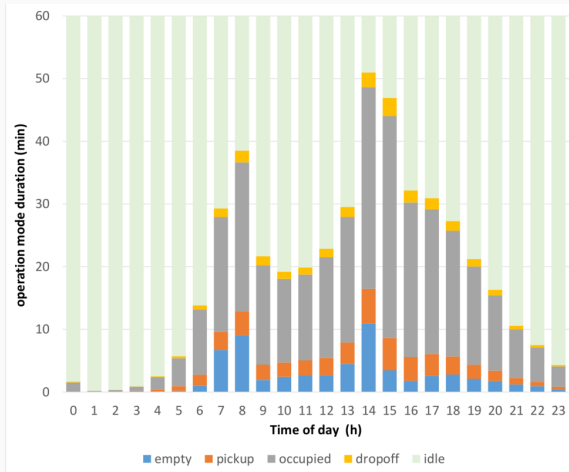
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# Case Study: Simulation of City-Wide Autonomous Vehicle Network Deployment - Results 100'000 AVs



**Figure 4:** Passenger wait times for each hour

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**Figure 5:** Average operation mode split for each hour

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- Fleet size determined by peak hours
- Drive time increases by 17% due to empty runs

# Case Study: Autonomous Taxis could greatly reduce GHG emissions<sup>8</sup>

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<sup>8</sup>Jeffery B. Greenblatt and Samveg Saxena. Autonomous taxis could greatly reduce greenhouse-gas emissions of US light-duty vehicles, *Nature Climate Change* 5, pp. 860–863, 2015

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- Estimate the GHG emissions by 2030 assuming all taxis are replaced by autonomous vehicles

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- Efficiency gains will compensate the increase in total distance travelled

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# Outline

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Remaining Work

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## Positive vs. Rebound Effect<sup>9</sup>

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- Efficient driving and routing

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## Positive vs. Rebound Effect<sup>9</sup>

- Efficient driving and routing
- Higher occupancy per vehicle

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- Efficient driving and routing
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- Public transport popularity decrease

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- Ecological, societal and economical impacts
- Total impact depends on adoption rate



Thanks for listening! Do you have any questions?

# Case Study: Estimating Potential Increase in Travel with Autonomous Vehicles<sup>10</sup>

- Studies potential increase in total vehicle distance travelled
- Increase due to senior citizens, non-drivers, and users with prohibiting medical conditions.
- Estimated 14% increase in total distance driven, due to increase in mobility of non-driving demographic

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<sup>10</sup>Corey D. Harper, Chris T. Hendrickson, Sonia Mangones and Constantine Samaras. Estimating potential increases in travel with autonomous vehicles for the non-driving, elderly and people with travel-restrictive medical conditions, Transportation Research Part C: Emerging Technologies, 72 (1), pp. 1-9, 2016