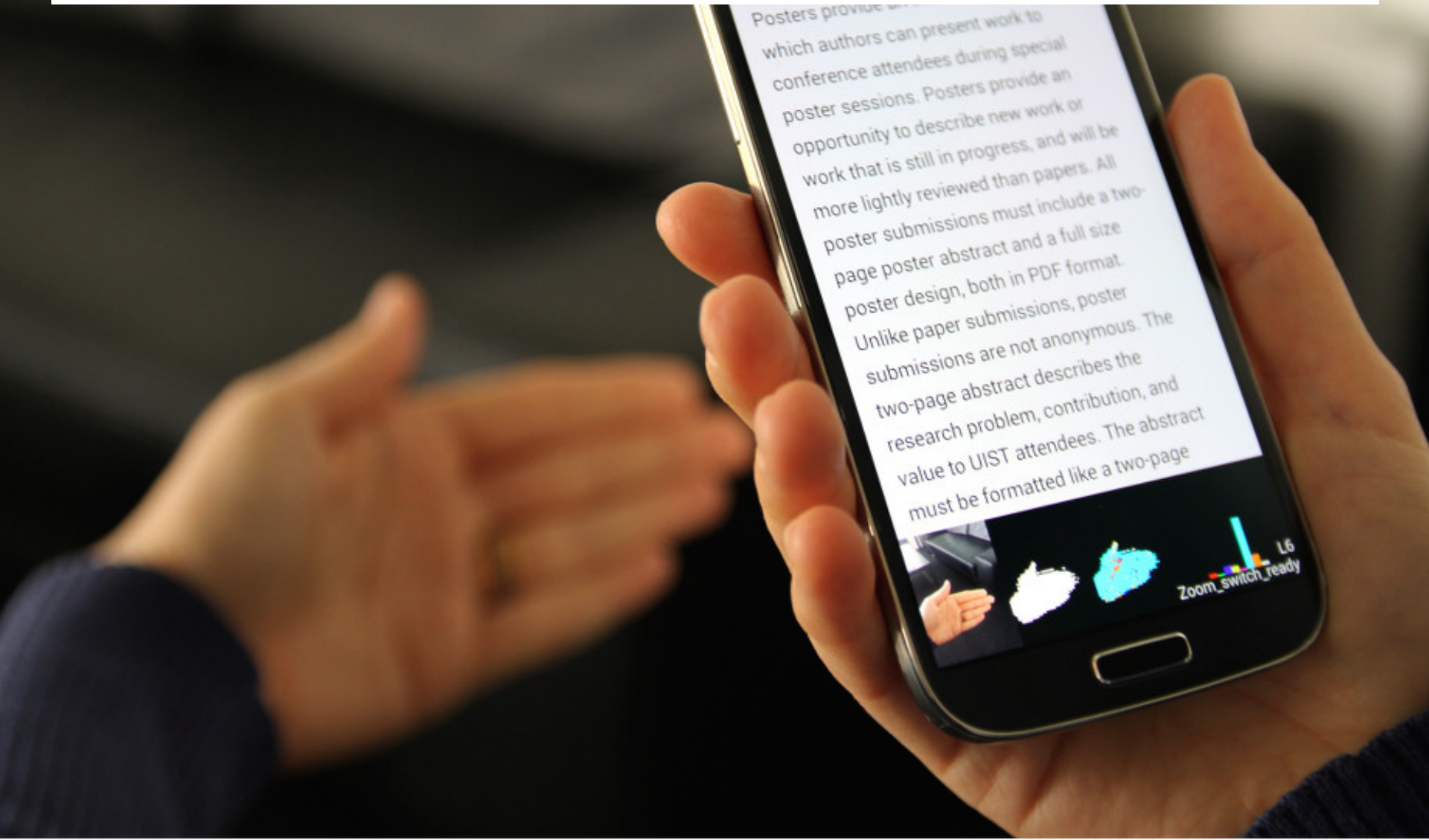


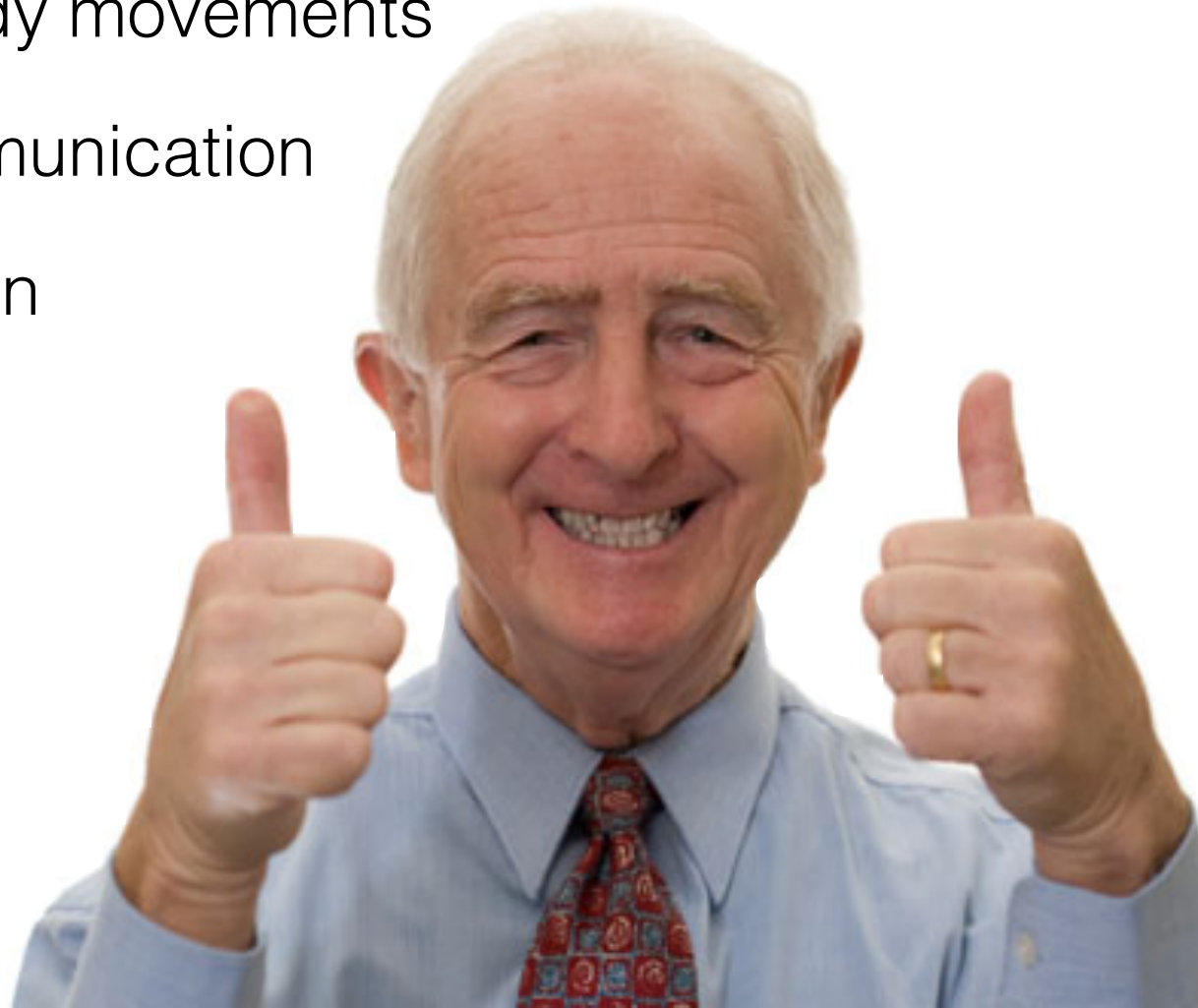
Margarita Grinvald

Gesture recognition for Smartphones/Wearables



Gestures

- hands, face, body movements
- non-verbal communication
- human interaction



Gesture recognition

- interface with computers
- increase usability
- intuitive interaction

Gesture sensing

- Contact type:
 - Touch based
- Non-contact type:
 - Device gesture
 - Vision based
 - Electrical Field Sensing (EFS)

Issues on mobile devices

- miniaturisation
- lack tactile clues
- no link between physical and digital interactions
- computational power

Approaches

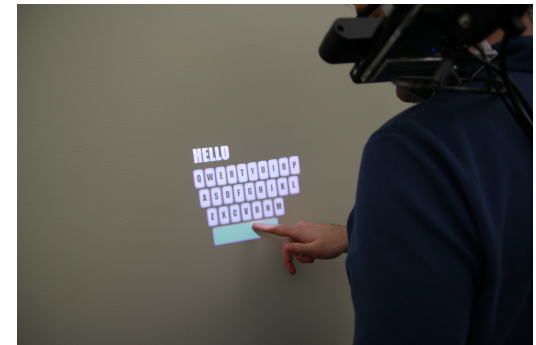
- augment environment with digital information



Sixthsense [Mistry et al. SIGGRAPH 2009]



Skinput [Harrison et al. CHI 2010]



OmniTouch [Harrison et al. UIST 2011]

Approaches

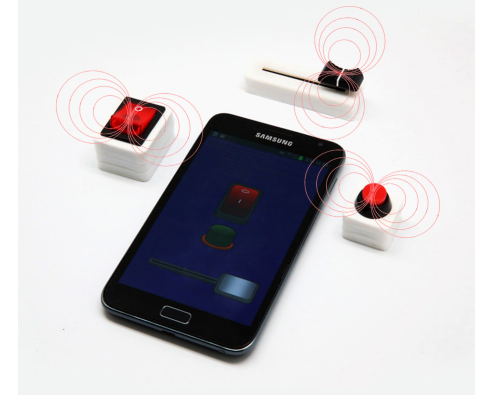
- augment hardware



In-air typing interface for mobile devices with vibration feedback
[Niikura et al. SIGGRAPH 2010]



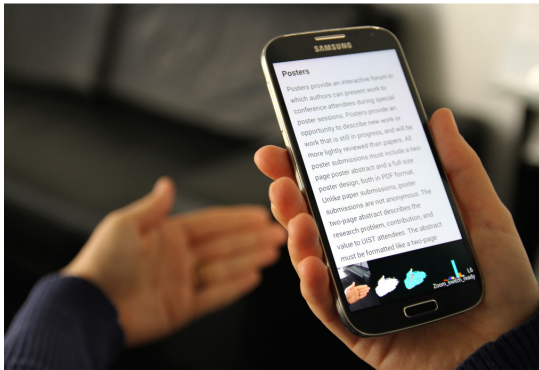
A low-cost transparent electric field sensor for 3D interaction
[Le Goc et al. CHI 2014]



MagGetz [Hwang et al. UIST 2013]

Approaches

- efficient algorithms



In-air gestures around unmodified mobile devices
[Song et al. UIST 2014]

- combine devices

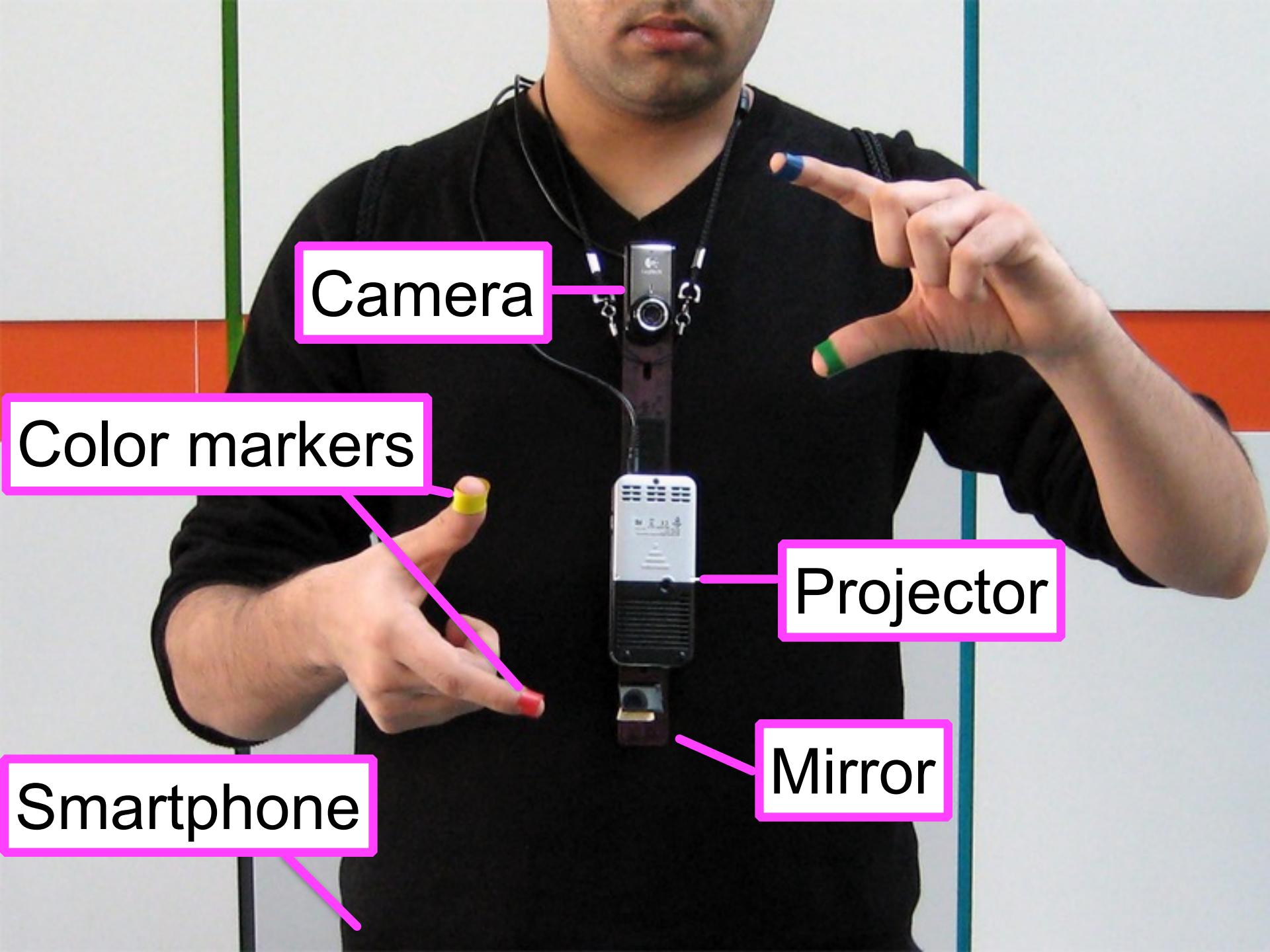


Duet: Exploring Joint interactions on a smart phone
and a smart watch
[Chen et al. CHI 2014]

Sixthsense

[Mistry et al. SIGGRAPH 2009]

- augment environment with visual information
- interact through natural hand gestures
- wearable to be truly mobile



Camera

Color markers

Smartphone

Projector

Mirror

Support for arbitrary surfaces



Support for multitouch



Limitations

- inability track surfaces
- differentiate hover and click
- accuracy limitations

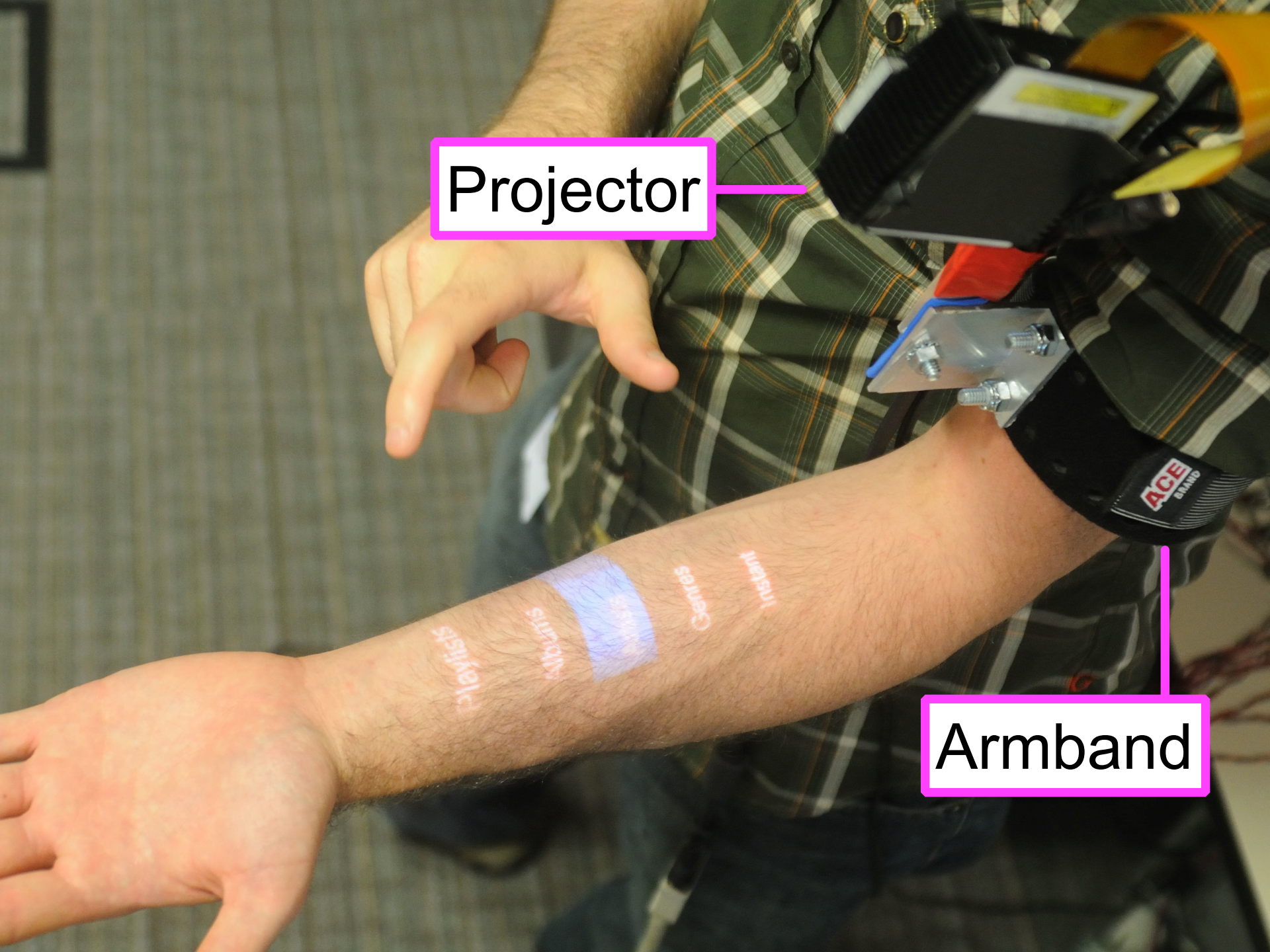
Skinput

[Harrison et al. CHI 2010]

- skin as input canvas
- wearable bio-acoustic sensor
- localisation of finger tap

Projector

Armband



Mechanical phenomena

- finger tap on skin generates acoustic energy
 - some energy becomes sound waves
 - some energy transmitted through the arm

Transverse waves



Longitudinal waves

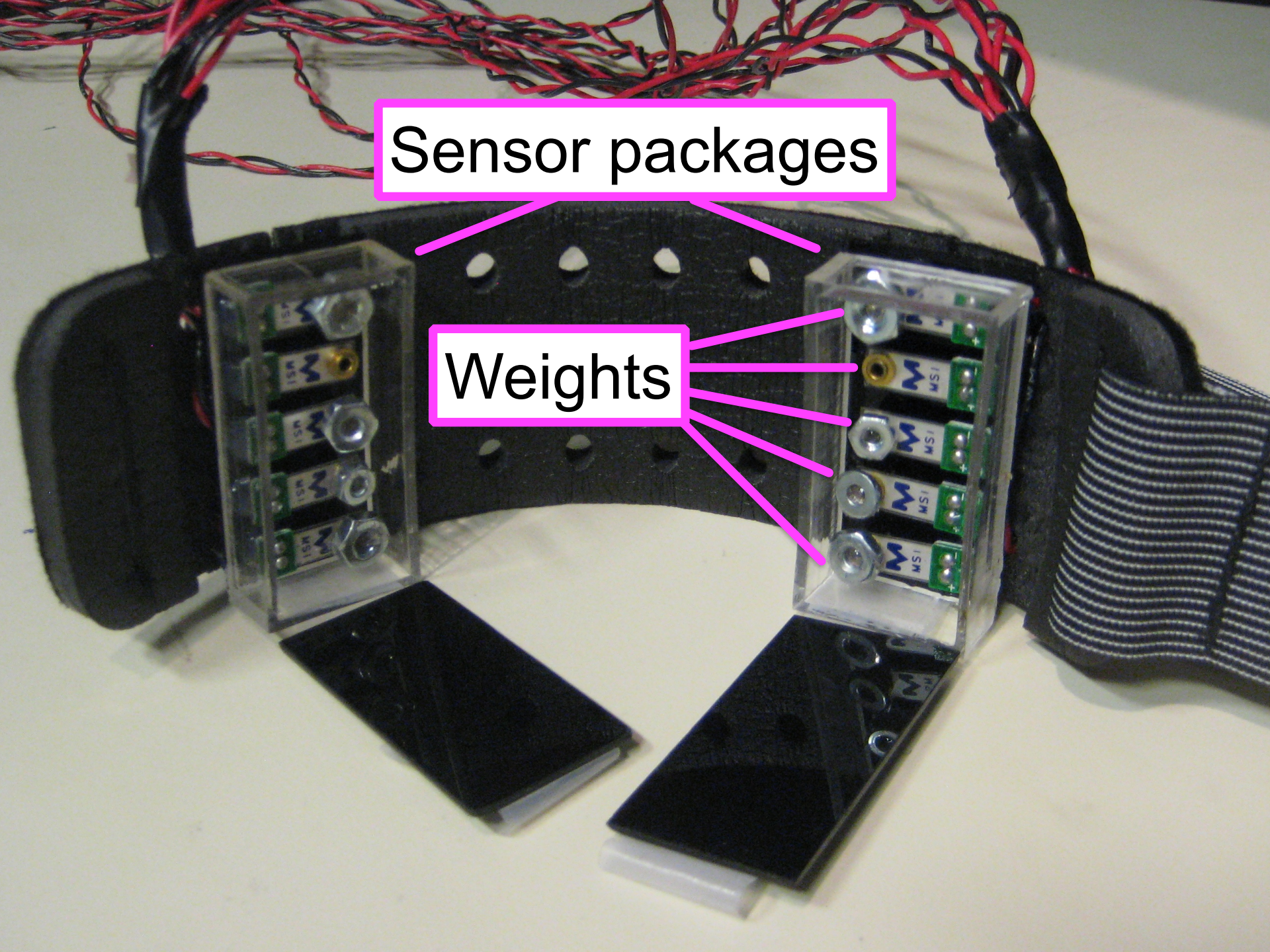


Sensing

- array of tuned vibrations sensors
- sensitive only to motion perpendicular to skin
- two sensing arrays to disambiguate different armband positions.

Sensor packages

Weights



Tap localisation

- sensor data segmented into taps
- ML classification of location
- initial training stage



Limitations

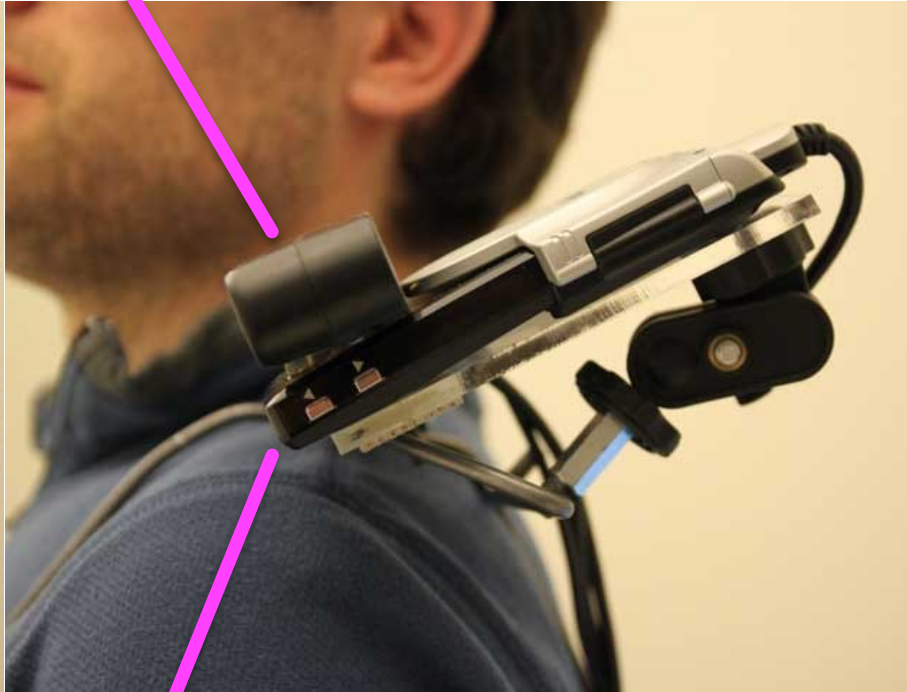
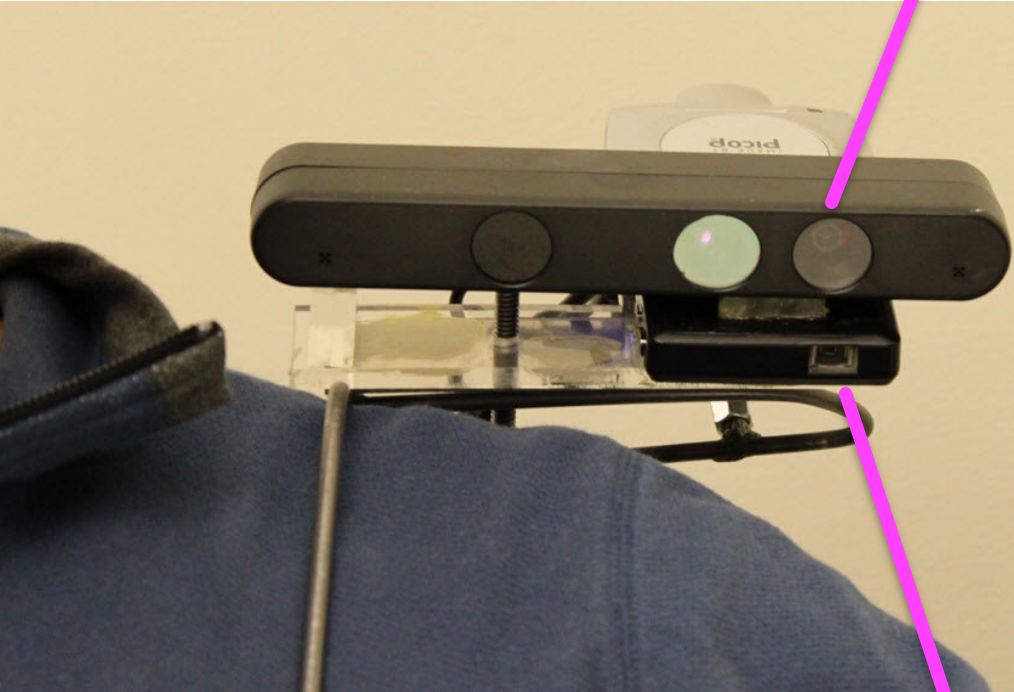
- lack of support of other surfaces than skin
- no multitouch support
- no touch drag movement

OmniTouch

[Harrison et al. UIST 2011]

- appropriate on demand ad hoc surfaces
- depth sensing and projection wearable
- depth driven template matching

Depth Camera

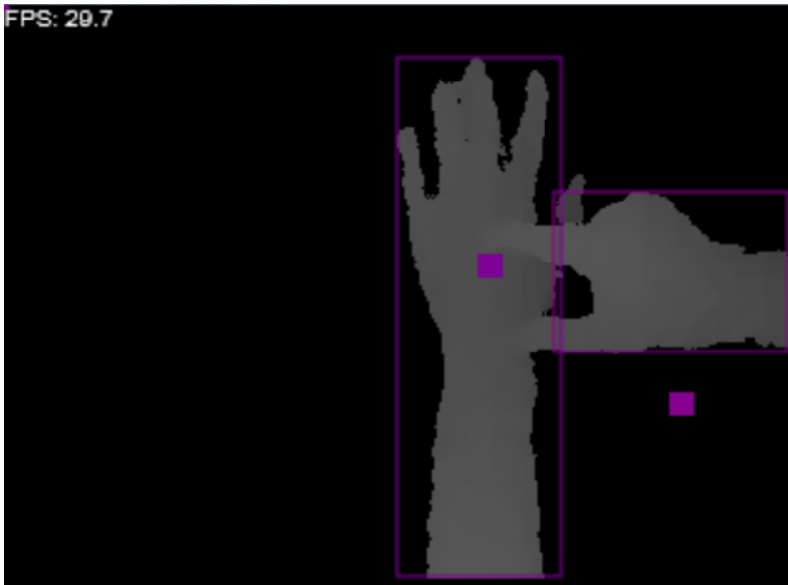


Projector

Finger tracking

- multitouch finger tracking on arbitrary surfaces
- no calibration or training
- resolve position and distinguish hover from click

Finger segmentation



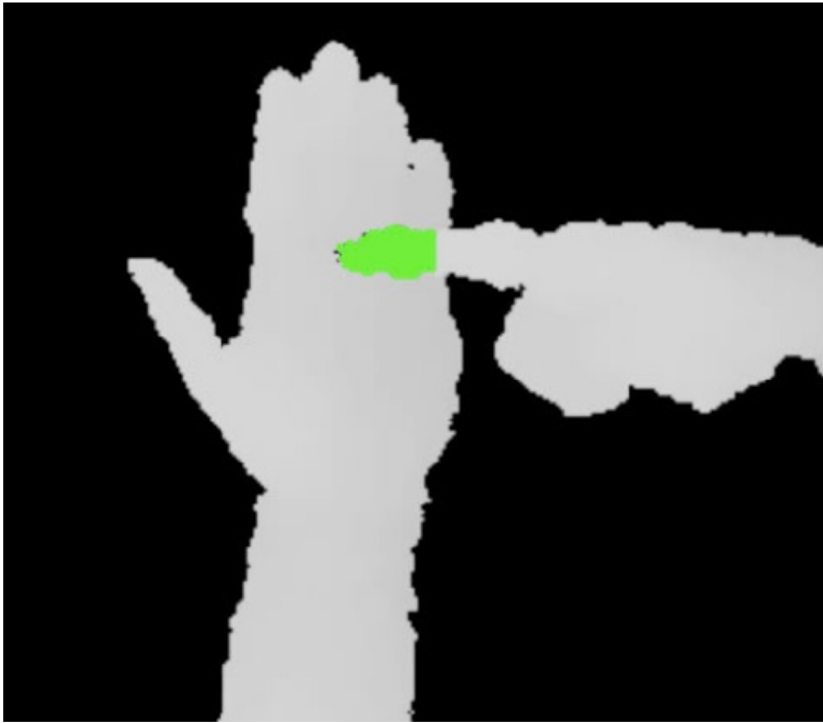
Depth map

Finger segmentation



Candidates

Click detection



Finger hovering

On demand interfaces

- expand application space with graphical feedback
- track surface on which rendered
- update interface as surface moves

Interface 'glued' to surface



In-air typing interface for mobile devices with vibration feedback

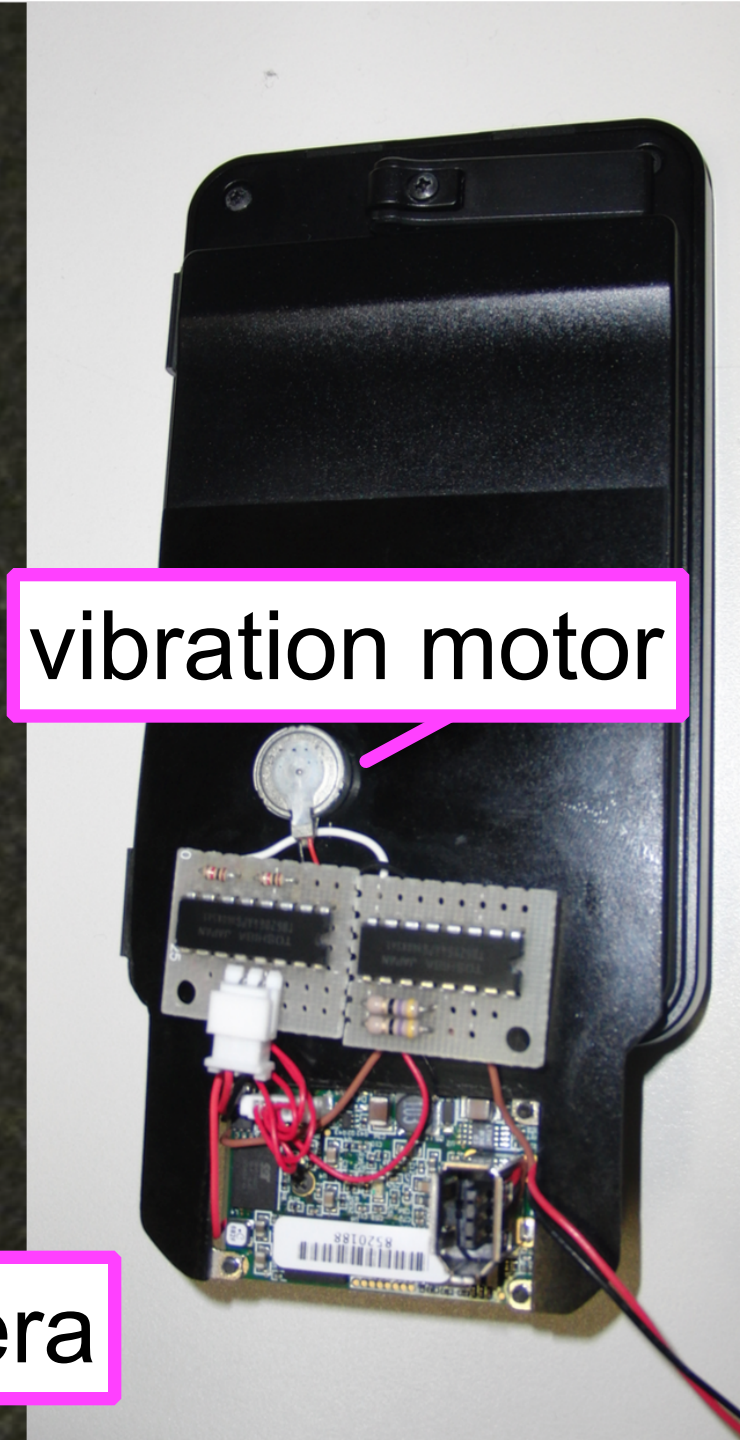
[Niikura et al. SIGGRAPH 2010]

- vision based 3D input interface
- detect keystroke action in the air
- provide vibration feedback



white LEDs

Camera



vibration motor

Tracking

- high frame rate camera
- wide angle lens needs distortion correction
- skin colour extraction to detect fingertip
- estimate fingertip translation, rotation and scale

Keystroke feedback

- difference of the dominant frequency of the fingertips scale to detect keystroke
- tactile feedback is important
- vibration feedback is conveyed after a keystroke

Vision limitations

- camera is rich and flexible but with limitations
- minimal distance between sensor and scene
- sensitivity to lighting changes
- computational overheads
- high power requirements

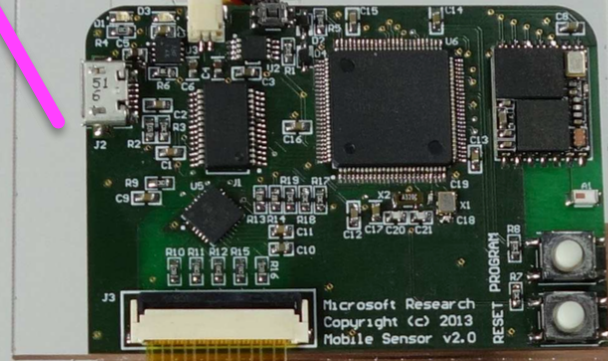
A low-cost transparent electric field sensor for 3D interaction

[Le Goc et al. CHI 2014]

- smartphone augmented with EFS
- resilient to illumination changes
- mapping measurements to 3D finger positions.

Drive electronics

Electrode array



Recognition

- microchip built-in 3D positioning has low accuracy
- Random Decision Forests for regression on raw signal data
- speed and accuracy

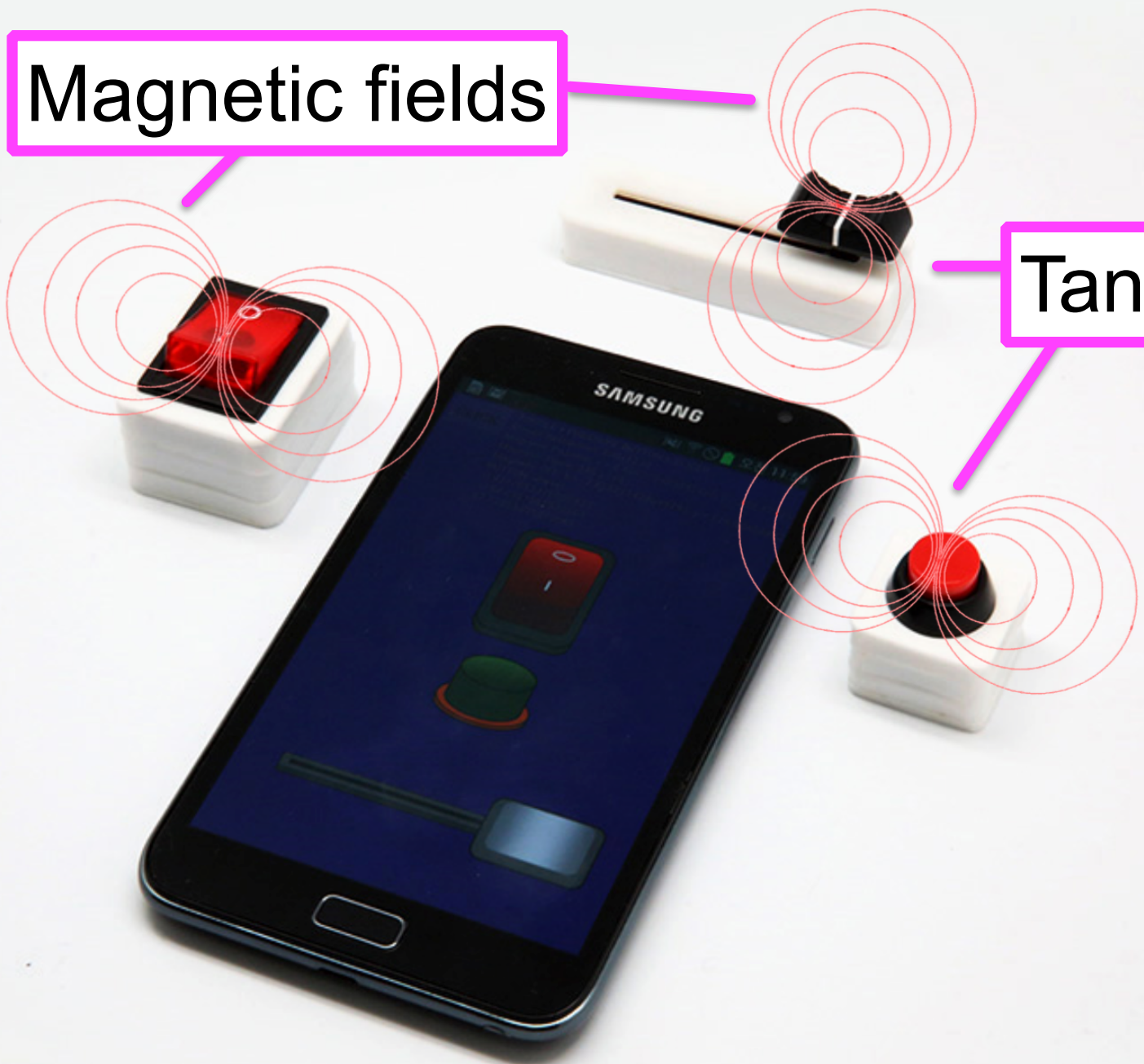
MagGetz

[Hwang et al. UIST 2013]

- tangible control widgets for richer tactile clues
- wider interaction area
- low cost and user configurable unpowered magnets

Magnetic fields

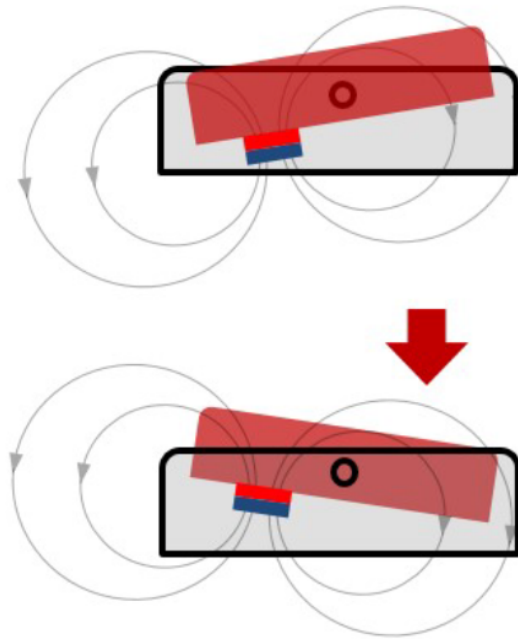
Tangibles



Tangibles

- traditional physical input controls with magnets
- magnetic traces change on widget state change
- track physical movement of control widgets

Tangibles magnetism



Toggle switch

Limitations

- object damage by magnets
- magnetometer limitations

In-air gestures around unmodified mobile devices

[Song et al. UIST 2014]

- extend interaction space with gesturing
- mobile devices RGB camera
- robust ML based algorithm

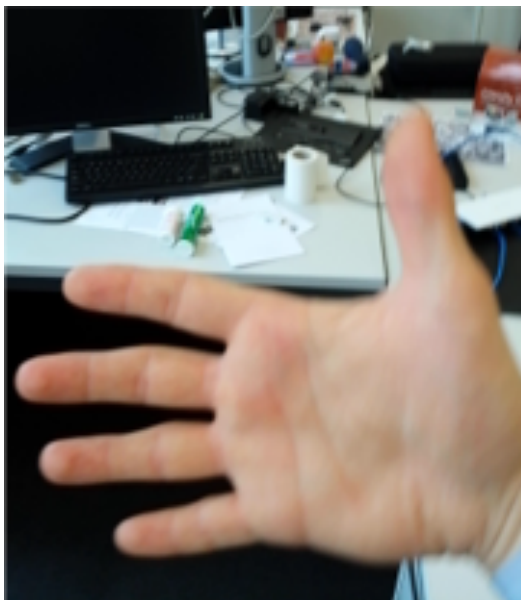
Gesture recognition

- detection of salient hand parts (fingertips)
- works without relying on highly discriminative depth data and rich computational resources
- no strong assumption about users environment
- reasonably robust to rotation and depth variation

Recognition algorithm

- real time algorithm
- pixel labelling with random forests
- techniques to reduce memory footprint of classifier

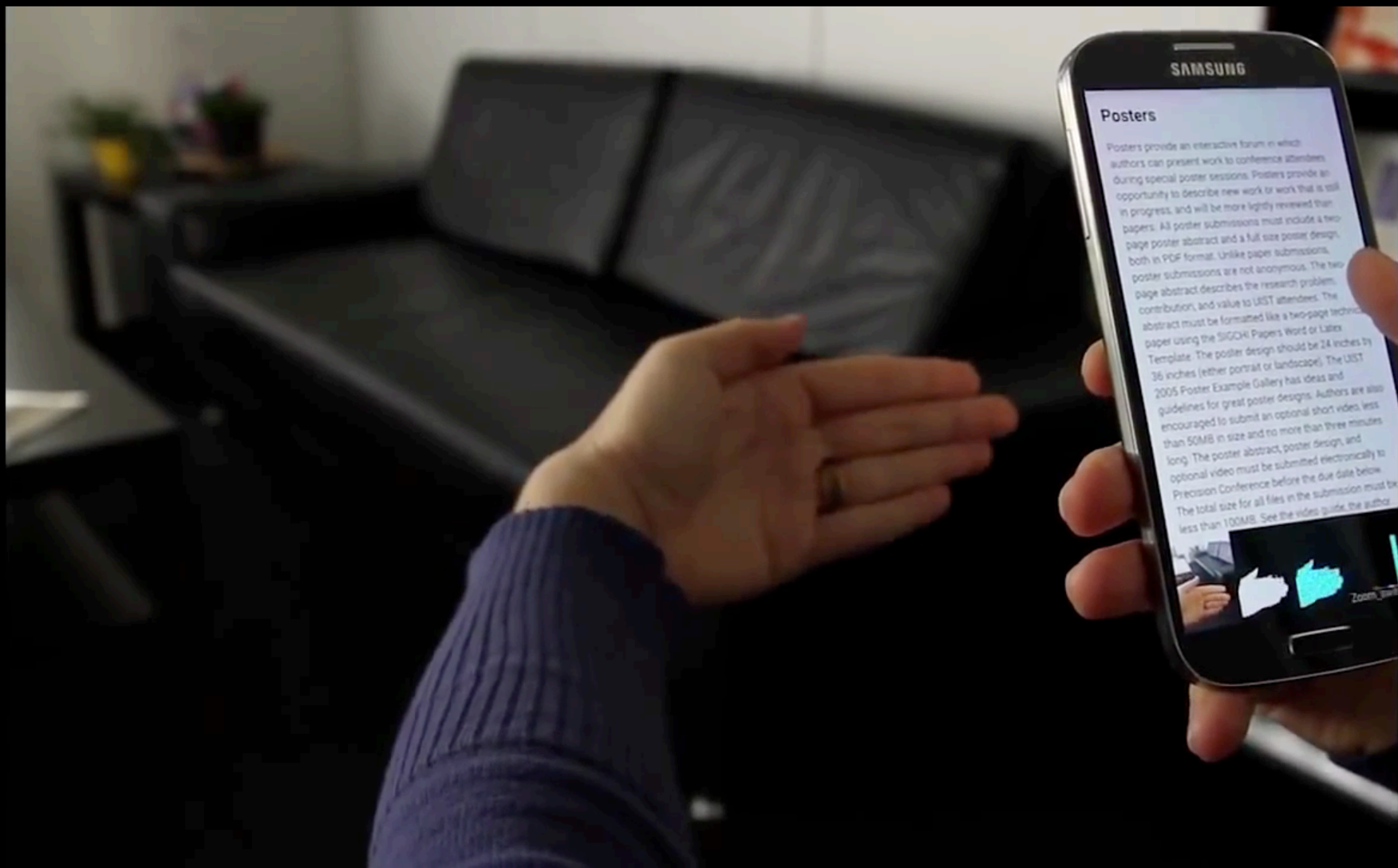
Recognition steps



RGB input

Applications

- division of labor
- works on many devices
- new apps enabled just by collecting new data





Duet: Exploring joint interactions on a smart phone and a smart watch

[Chen et al. CHI 2014]

- beyond usage of single device
- allow individual input and output
- joint interactions smart phone and smart watch

Design space theory

- conversational duet
- foreground interaction
- background interaction

Design space

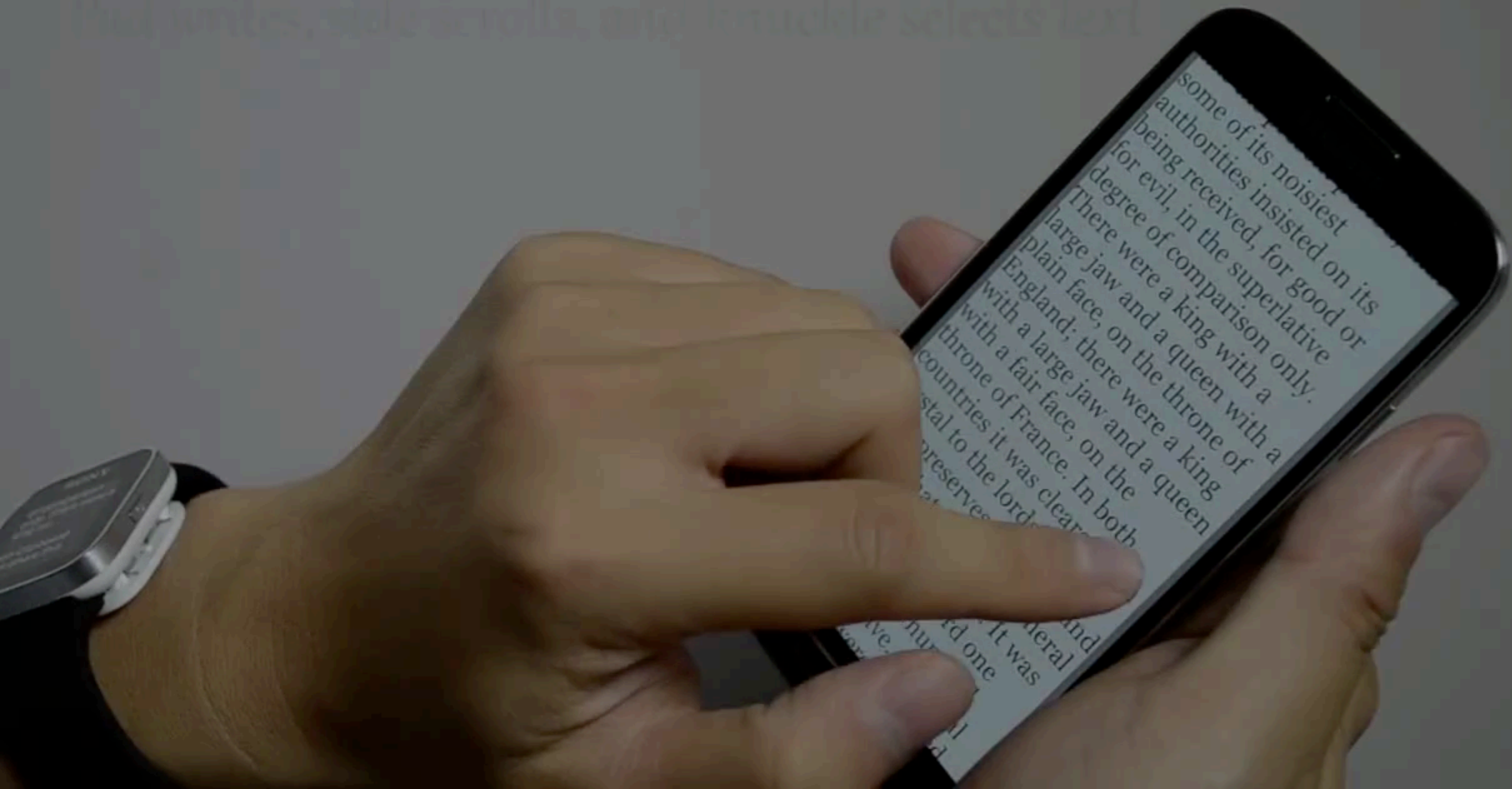
	Watch Foreground	Watch Background
Phone Foreground	<p>Duet:</p> <ul style="list-style-type: none">• Phone as a primary input and output platform;• Watch as an input device or extended display.	<p>Duet:</p> <ul style="list-style-type: none">• Phone as a primary input and output platform;• Watch as a sensor.
Phone Background	<p>Current commercial designs:</p> <ul style="list-style-type: none">• Phone as an inactivated information portal• Watch as a viewport or remote control	<p>Prior research:</p> <ul style="list-style-type: none">• Both phone and watch used for context and activity sensing



Design space

	Watch Foreground	Watch Background
Phone Foreground	<p>Duet:</p> <ul style="list-style-type: none">• Phone as a primary input and output platform;• Watch as an input device or extended display.	<p>Duet:</p> <ul style="list-style-type: none">• Phone as a primary input and output platform;• Watch as a sensor.
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Pinch writes, side scrolls, and knuckle selects text



Gesture recognition

- ML techniques on accelerometer data
- handedness recognition
- promising accuracy

Summary

- wearables extend interaction space to everyday surfaces
- augmented hardware in general provides an intuitive interface
- no additional hardware is preferable but there are still computational limitations
- combination of devices may be redundant

References

- SixthSense: a wearable gestural interface [Mistry et al. SIGGRAPH 2009]
- Skinput: Appropriating the Body As an Input Surface [Harrison et al. CHI 2010]
- OmniTouch: Wearable Multitouch Interaction Everywhere [Harrison et al. UIST 2011]
- In-air typing interface for mobile devices with vibration feedback [Niikura et al. SIGGRAPH 2010]
- A Low-cost Transparent EF Sensor for 3D Interaction on Mobile Devices [Le Goc et al. CHI 2014]
- MagGetz: customizable passive tangible controllers on and around [Hwang et al. UIST 2013]
- In-air gestures around unmodified mobile devices mobile devices [Song et al. UIST 2014]
- Duet: Exploring Joint Interactions on a Smart Phone and a Smart Watch [Chen et al. CHI 2014]